19-0410; Rev 3; 7/96

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±15kV ESD-Protected, Slew-Rate-Limited, Low-Power, RS-485/RS-422 Transceivers

#### General Description

The MAX481E, MAX483E, MAX485E, MAX487E–MAX491E, and MAX1487E are low-power transceivers for RS-485 and RS-422 communications in harsh environments. Each driver output and receiver input is protected against ±15kV electrostatic discharge (ESD) shocks, without latchup. These parts contain one driver and one receiver. The MAX483E, MAX487E, MAX488E, and MAX489E feature reduced slewrate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, thus allowing error-free data transmission up to 250kbps. The driver slew rates of the MAX481E, MAX485E, MAX490E, MAX491E, and MAX1487E are not limited, allowing them to transmit up to 2.5Mbps.

These transceivers draw as little as 120µA supply current when unloaded or when fully loaded with disabled drivers (see *Selection Table*). Additionally, the MAX481E, MAX483E, and MAX487E have a low-current shutdown mode in which they consume only 0.5µA. All parts operate from a single +5V supply.

Drivers are short-circuit current limited, and are protected against excessive power dissipation by thermal shutdown circuitry that places their outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a logic-high output if the input is open circuit.

The MAX487E and MAX1487E feature quarter-unit-load receiver input impedance, allowing up to 128 transceivers on the bus. The MAX488E–MAX491E are designed for full-duplex communications, while the MAX481E, MAX483E, MAX485E, MAX487E, and MAX1487E are designed for half-duplex applications. For applications that are not ESD sensitive see the pin- and function-compatible MAX481, MAX483, MAX485, MAX487–MAX491, and MAX1487.

\_Applications

Low-Power RS-485 Transceivers Low-Power RS-422 Transceivers Level Translators Transceivers for EMI-Sensitive Applications Industrial-Control Local Area Networks

#### Features

- ESD Protection: ±15kV—Human Body Model
- Slew-Rate Limited for Error-Free Data Transmission (MAX483E/487E/488E/489E)
- Low Quiescent Current: 120µA (MAX483E/487E/488E/489E) 230µA (MAX1487E) 300µA (MAX481E/485E/490E/491E)
- ♦ -7V to +12V Common-Mode Input Voltage Range
- Three-State Outputs
- ✤ 30ns Propagation Delays, 5ns Skew
- (MAX481E/485E/490E/491E/1487E)
- Full-Duplex and Half-Duplex Versions Available
- Allows up to 128 Transceivers on the Bus (MAX487E/MAX1487E)
- Current Limiting and Thermal Shutdown for Driver Overload Protection

#### Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX481ECPA	0°C to +70°C	8 Plastic DIP
MAX481ECSA	0°C to +70°C	8 SO
MAX481EEPA	-40°C to +85°C	8 Plastic DIP
MAX481EESA	-40°C to +85°C	8 SO

Ordering Information continued on last page.

#### Selection Table

PART NUMBER	HALF/FULL DUPLEX	DATA RATE (Mbps)	SLEW-RATE LIMITED	LOW-POWER SHUTDOWN	RECEIVER/ DRIVER ENABLE	QUIESCENT CURRENT (µA)	NUMBER OF TRANSMITTERS ON BUS	PIN COUNT
MAX481E	Half	2.5	No	Yes	Yes	300	32	8
MAX483E	Half	0.25	Yes	Yes	Yes	120	32	8
MAX485E	Half	2.5	No	No	Yes	300	32	8
MAX487E	Half	0.25	Yes	Yes	Yes	120	128	8
MAX488E	Full	0.25	Yes	No	No	120	32	8
MAX489E	Full	0.25	Yes	No	Yes	120	32	14
MAX490E	Full	2.5	No	No	No	300	32	8
MAX491E	Full	2.5	No	No	Yes	300	32	14
MAX1487E	Half	2.5	No	No	Yes	230	128	8

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#### ABSOLUTE MAXIMUM RATINGS

Supply Voltage (V <sub>CC</sub> )
Control Input Voltage (RE, DE)0.5V to (V <sub>CC</sub> + 0.5V)
Driver Input Voltage (DI)0.5V to (V <sub>CC</sub> + 0.5V)
Driver Output Voltage (Y, Z; A, B)8V to +12.5V
Receiver Input Voltage (A, B)8V to +12.5V
Receiver Output Voltage (RO)0.5V to (V <sub>CC</sub> + 0.5V)
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
8-Pin Plastic DIP (derate 9.09mW/°C above +70°C)727mW

14-Pin Plastic DIP (derate 10.00mW/°C above +70°C)..800mW 8-Pin SO (derate 5.88mW/°C above +70°C)......471mW 14-Pin SO (derate 8.33mW/°C above +70°C)......667mW Operating Temperature Ranges

MAX4C/MAX1487EC_ A	0°C to +70°C
MAX4E/MAX1487EE_ A	40°C to +85°C
Storage Temperature Range	65°C to +160°C
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

(V\_CC = 5V  $\pm$ 5%, TA = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.) (Notes 1, 2)

Vod1		CONDITIONS				
					5	V
V	R = 50Ω (RS-422)		2			V
V <sub>OD2</sub>	R = 27Ω (RS-485), Figure 8		1.5		5	v
ΔV <sub>OD</sub>	R = $27\Omega$ or $50\Omega$ , Figure 8				0.2	V
Voc	R = $27\Omega$ or $50\Omega$ , Figure 8				3	V
ΔV <sub>OD</sub>	R = $27\Omega$ or $50\Omega$ , Figure 8				0.2	V
Vih	DE, DI, RE		2.0			V
VIL	DE, DI, RE				0.8	V
l <sub>IN1</sub>	DE, DI, RE				±2	μA
	DE = 0V; V <sub>CC</sub> = 0V or 5.25V,	V <sub>IN</sub> = 12V			1.0	mA
I <sub>IN2</sub>	all devices except MAX487E/MAX1487E	$V_{IN} = -7V$			-0.8	
	MAX487E/MAX1487E,	$V_{IN} = 12V$			0.25	mA
	$DE = 0V, V_{CC} = 0V \text{ or } 5.25V$	$V_{IN} = -7V$			-0.2	IIIA
V <sub>TH</sub>	$-7V \le V_{CM} \le 12V$		-0.2		0.2	V
$\Delta V_{TH}$	$V_{CM} = 0V$			70		mV
Voh	$I_{O} = -4mA$ , $V_{ID} = 200mV$		3.5			V
Vol	$I_{O} = 4mA, V_{ID} = -200mV$				0.4	V
I <sub>OZR</sub>	$0.4V \le V_O \le 2.4V$				±1	μA
PIN	-7V ≤ V <sub>CM</sub> ≤ 12V, all devices of MAX487E/MAX1487E	except	12			kΩ
NIN	-7V ≤ V <sub>CM</sub> ≤ 12V, MAX487E/N	IAX1487E	48			kΩ
	Voc           ΔVod           VIH           VIL           IIN1           IN2           VTH           ΔVTH           VOL	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	$\begin{array}{ c c c c } \Delta V_{OD} & R = 27\Omega \text{ or } 50\Omega, \text{ Figure 8} \\ \hline & & \\ \hline & V_{OC} & R = 27\Omega \text{ or } 50\Omega, \text{ Figure 8} \\ \hline & & \\ \hline \hline & & \\ \hline \hline & & \\ \hline \hline & & \\ \hline & & \\ \hline \hline$	$\begin{array}{ c c c c c } \Delta V_{OD} & R = 27\Omega \mbox{ or } 50\Omega, \mbox{ Figure 8} \\ \hline & & \\ \hline \hline & & \\ \hline & & \\ \hline & & \\ \hline & & \\ \hline \hline & & \\ \hline \hline \\ \hline & & \\ \hline \hline & & \\ \hline \hline \\ \hline & $	$ \begin{array}{ c c c c c } \Delta V_{OD} & R = 27\Omega \mbox{ or } 50\Omega, \mbox{ Figure 8} \\ \hline & & \\ \hline \hline & & \\ \hline & & \\ \hline & & \\ \hline & & \\ \hline \hline & & \\ \hline \hline \\ \hline & & \\ \hline \hline & & \\ \hline \hline \\ \hline \\$	$ \begin{array}{ c c c c } \Delta V_{OD} & R = 27\Omega \mbox{ or } 50\Omega, \mbox{ Figure 8} & 0.2 \\ \hline & & & & & & & & & & & & & & & & & &$

PARAMETER	SYMBOL	CONDITIONS			MIN	TYP	MAX	UNITS
		MAX488E/MAX489E, DE, DI, $\overline{RE} = 0V$ or V <sub>CC</sub>			120	250		
		MAX490E/MAX491E, DE, DI, $\overline{RE}$ = 0V or V <sub>C</sub>	C			300	500	
Ne Leed Consels Consent		MAX481E/MAX485E,	DE = VCC			500	900	1
No-Load Supply Current (Note 3)	Icc	$\overline{RE} = 0V \text{ or } V_{CC}$	DE = OV			300	500	μA
(		MAX1487E,	$DE = V_{CC}$			300	500	]
		$\overline{RE} = 0V \text{ or } V_{CC}$	DE = 0V			230	400	]
			DE = V <sub>CC</sub>	MAX483E		350	650	1
		MAX483E/MAX487E, $\overline{RE} = 0V \text{ or } V_{CC}$		MAX487E		250	400	]
			DE = 0V			120	250	
Supply Current in Shutdown	ISHDN	MAX481E/483E/487E,	$DE = 0V, \overline{RE} =$	VCC		0.5	10	μΑ
Driver Short-Circuit Current, $V_O = High$	IOSD1	-7V ≤ V <sub>O</sub> ≤12V (Note 4	)		35		250	mA
Driver Short-Circuit Current, V <sub>O</sub> = Low	IOSD2	-7V ≤ V <sub>O</sub> ≤12V (Note 4	)		35		250	mA
Receiver Short-Circuit Current	IOSR	0V ≤ V <sub>O</sub> ≤ V <sub>CC</sub>			7		95	mA
ESD Protection		A, B, Y and Z pins, tested	l using Human B	ody Model		±15		kV
	χ, uniess ou	nerwise noted.) (Notes 1	, 2)			,	AX148	
PARAMETER	SYMBOL		, 2) ITIONS		MIN	ТҮР	МАХ	
PARAMETER		COND Figures 10 and 12, RD	ITIONS		10		<b>MAX</b> 60	UNITS
PARAMETER Driver Input to Output	SYMBOL	$\label{eq:cond} \begin{array}{c} \textbf{COND} \\ Figures 10 and 12, R_D \\ C_{L1} = C_{L2} = 100 pF \end{array}$	<b>ITIONS</b> $FF = 54\Omega$ ,			ТҮР	MAX	
PARAMETER Driver Input to Output	SYMBOL t <sub>PLH</sub>	COND Figures 10 and 12, RD	<b>ITIONS</b> $FF = 54\Omega$ ,		10	<b>TYP</b> 40	<b>MAX</b> 60	UNITS
PARAMETER Driver Input to Output	SYMBOL       tplh       tphl	$\label{eq:cond} \begin{array}{c} \textbf{COND} \\ Figures 10 and 12, R_D \\ C_{L1} = C_{L2} = 100 pF \end{array}$	<b>ITIONS</b> FF = 54Ω, = 54Ω, CL1 = C	· · ·	10 10 3	<b>TYP</b> 40 40	<b>MAX</b> 60 60	UNITS
PARAMETER Driver Input to Output Driver Output Skew to Output	SYMBOL       tplh       tphL       tskew	$\label{eq:cond} \begin{array}{c} \text{COND} \\ \text{Figures 10 and 12, RD} \\ \text{C}_{L1} = \text{C}_{L2} = 100 \text{pF} \\ \text{Figures 10 and 12, RDIFF} \\ \text{Figures 10 and 12, MA} \end{array}$	<b>ITIONS</b> <sub>FF</sub> = 54Ω, = 54Ω, C <sub>L1</sub> = C <sub>I</sub> X481E, MAX485E	, MAX1487E	10	<b>TYP</b> 40 40 5	<b>MAX</b> 60 60 10	NS ns
PARAMETER Driver Input to Output Driver Output Skew to Output	SYMBOL       tplh       tphL       tskew	$\label{eq:condition} \hline \begin{tabular}{lllllllllllllllllllllllllllllllllll$	<b>ITIONS</b> FF = 54Ω, = 54Ω, C <sub>L1</sub> = C <sub>l</sub> X481E, MAX485E X490EC/E, MA	, MAX1487E X491EC/E	10 10 3	<b>TYP</b> 40 40 5 20	MAX 60 60 10 40	NS ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time	SYMBOL       tPLH       tPHL       tSKEW       tR, tF	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DI} \\ C_{L1} = C_{L2} = 100 pF \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} = 54\Omega, \\ C_{L1} = C_{L2} = 100 pF \\ \hline \textbf{MA} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 11 and 13, C_{L} \\ \hline \hline Figures 11 and 13, C_{L} \\ \hline \end{array}$	ITIONS           FF = 54Ω,           = 54Ω, CL1 = Cl           X481E, MAX485E           X490EC/E, MA           = 100pF, S2 cl           = 100pF, S1 cl	, MAX1487E X491EC/E losed losed	10 10 3	TYP           40           40           5           20           20	MAX 60 60 10 40 25	UNITS ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DIF} \\ \hline C_{L1} = C_{L2} = 100 pF \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 pF \\ \hline \textbf{MA} \\ \hline Figures 11 and 13, C_{L} \\ \hline \end{array}$	ITIONS           FF = 54Ω,           = 54Ω, CL1 = Cl           X481E, MAX485E           X490EC/E, MA           = 100pF, S2 cl           = 100pF, S1 cl           = 15pF, S1 clo	, MAX1487E X491EC/E losed losed sed	10 10 3	TYP           40           40           5           20           20           45           45           45           45	MAX           60           60           10           40           25           70           70           70           70	UNITS ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low	SYMBOL           tPLH           tPHL           tSKEW           tR, tF           tZH           tZL	$\label{eq:constraint} \begin{array}{c} \text{COND} \\ Figures 10 and 12, R_{DIF} \\ C_{L1} = C_{L2} = 100 pF \\ Figures 10 and 12, R_{DIFF} \\ Figures 10 and 12, R_{DIFF} = 54\Omega, \\ C_{L1} = C_{L2} = 100 pF \\ Figures 11 and 13, C_{L} \\ Figures 11 and 13 \\ Figures 11 and 13$	ITIONS           FF = 54Ω,           = 54Ω, CL1 = Cl           X481E, MAX485E           X490EC/E, MA           = 100pF, S2 cl           = 100pF, S1 cl           = 15pF, S1 clo           = 15pF, S2 clo	MAX1487E X491EC/E losed losed ised ised	10 10 3	TYP           40           40           5           20           20           45           45	MAX 60 60 10 40 25 70 70	UNITS ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low Driver Disable Time from High	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ       tHZ	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, RDIF \\ \hline CL1 = CL2 = 100pF \\ \hline Figures 10 and 12, RDIFF \\ \hline Figures 10 and 12, RDIFF = 54\Omega, \\ CL1 = CL2 = 100pF \\ \hline MA \\ \hline Figures 11 and 13, CL \\ \hline Figures 10 and 14, MA \\ \hline \end{tabular}$	ITIONS           FF = 54Ω,           = 54Ω, CL1 = Cl           X481E, MAX485E           X490EC/E, MA           = 100pF, S2 cl           = 100pF, S1 cl           = 15pF, S1 clo           = 15pF, S2 clo	MAX1487E X491EC/E losed losed ised ised	10 10 3	TYP           40           40           5           20           20           45           45           45           45	MAX           60           60           10           40           25           70           70           70           70	UNITS ns ns ns ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low Driver Disable Time from High	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DIF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline \textbf{MA} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 10 and 14, \\ R_{DIFF} = 54\Omega, \\ C_{L1} = C_{L2} = 100 \text{pF} \\ \hline \textbf{MA} \\ \hline \end{array}$	TIONS         FF = 54Ω,         = 54Ω, CL1 = Cl         X481E, MAX485E         X490EC/E, MA         = 100pF, S2 cl         = 100pF, S1 cl         = 15pF, S1 clo         = 15pF, S2 clo         X481E, MAX485E         X481E, MAX485E	, MAX1487E X491EC/E losed losed sed sed sed , MAX1487E	10 10 3 5	TYP           40           40           5           20           20           45           45           45           45	MAX           60           60           10           40           25           70           70           70           70           70	UNITS ns ns ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ       tHZ	COND           Figures 10 and 12, RD $C_{L1} = C_{L2} = 100$ pF           Figures 10 and 12, RD           Figures 10 and 12, RD $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100$ pF           Figures 11 and 13, CL           Figures 10 and 14, MA	TIONS         FF = 54Ω,         = 54Ω, CL1 = Cl         X481E, MAX485E         X490EC/E, MA         = 100pF, S2 cl         = 100pF, S1 cl         = 15pF, S1 clo         = 15pF, S2 clo         X481E, MAX485E         X481E, MAX485E	, MAX1487E X491EC/E losed losed sed sed sed , MAX1487E	10 10 3 5 20	TYP           40           40           5           20           20           45           45           45           45           60	MAX           60           10           40           25           70           70           70           200	UNITS ns ns ns ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low Driver Disable Time from High Receiver Input to Output   tPLH - tPHL   Differential	SYMBOL       tPLH       tPHL       tskew       tR, tF       tZH       tZL       tHZ       tHZ       tPLH, tPHL	$\label{eq:constraint} \hline $ \textbf{COND} $ Figures 10 and 12, $ R_{DI}$ $ C_{L1} = C_{L2} = 100 $ $ P $ $ Figures 10 and 12, $ R_{DIFF}$ $ Figures 10 and 12, $ R_{DIFF}$ $ Figures 10 and 12, $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $ $$	ITIONS $FF = 54\Omega$ , $= 54\Omega$ , $CL1 = Cl$ X481E, MAX485E           X490EC/E, MA $= 100pF$ , S2 cl $= 100pF$ , S1 cl $= 15pF$ , S1 clo $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA $= FF$ , S1 clo $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA           FF = 54Ω,	,MAX1487E X491EC/E losed losed sed sed ,MAX1487E X491EC/E	10 10 3 5 20	TYP           40           40           5           20           20           45           45           45           45           60           60	MAX           60           10           40           25           70           70           70           200	UNITS ns ns ns ns ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low Driver Disable Time from High Receiver Input to Output [ tpLH - tpHL   Differential Receiver Skew Receiver Enable to Output Low	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ       tHZ       tHZ       tSKD	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DIF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline \textbf{MA} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 10 and 14, R_{DIFF} = 54\Omega, \\ C_{L1} = C_{L2} = 100 \text{pF} \\ \hline \textbf{MA} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline Figures 10 and 14 \\ \hline Figures 10 and$	ITIONS $FF = 54\Omega$ , $= 54\Omega$ , $CL1 = Cl$ X481E, MAX485E           X490EC/E, MA $= 100pF$ , S2 cl $= 100pF$ , S1 cl $= 15pF$ , S1 clo $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA           FF = 54Ω, $= 15pF$ , S1 clo $= 15pF$ , S1 clo	,MAX1487E X491EC/E losed ised ised ,MAX1487E X491EC/E ised	10 10 3 5 20	TYP           40           40           5           20           20           45           45           45           60           60           5	MAX           60           60           10           40           25           70           70           70           200           150	NR NS NS NS NS NS NS NS
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from High Receiver Input to Output [ tpLH - tpHL ] Differential Receiver Enable to Output Low Receiver Enable to Output High Receiver Enable to Output High Receiver Disable Time from Low Receiver Disable Time from Low Receiver Enable to Output High Receiver Disable Time from Low Receiver Disable Time	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ       tPLH, tPHL       tSKD       tZL       tZL	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DIF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline$	ITIONS $FF = 54\Omega$ , $= 54\Omega$ , $CL1 = Cl$ X481E, MAX485E           X490EC/E, MA $= 100pF$ , S2 cl $= 100pF$ , S1 cl $= 15pF$ , S1 clo $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA           FF = 54Ω, $= 15pF$ , S1 clo $= 15pF$ , S1 clo $= 15pF$ , S2 clo $= 15pF$ , S1 clo	,MAX1487E X491EC/E losed losed sed sed x491EC/E X491EC/E sed sed sed sed	10 10 3 5 20	TYP           40           40           5           20           20           45           45           45           60           5           20           20           20           20           20           20           20           20           20           20           20           20           20	MAX 60 10 25 70 70 70 70 200 150	UNITS ns ns ns ns ns ns ns ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from High Receiver Input to Output [ tpLH - tpHL ] Differential Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable Time from Low Receiver Disable Time from High Recei	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ       tPLH, tPHL       tSKD       tZL       tZL	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DIF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline Figures 9 and 15, C_{RL} \\ \hline Figures 9 and 15, C_{RL} \\ \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \ Figures 9 and 15, C_{RL} \\ \hline \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	ITIONS $FF = 54\Omega$ , $= 54\Omega$ , $CL1 = Cl$ X481E, MAX485E           X490EC/E, MA $= 100pF$ , S2 cl $= 100pF$ , S1 cl $= 15pF$ , S1 clo $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA           FF = 54Ω, $= 15pF$ , S1 clo $= 15pF$ , S1 clo $= 15pF$ , S2 clo $= 15pF$ , S1 clo	,MAX1487E X491EC/E losed losed sed sed x491EC/E X491EC/E sed sed sed sed	10 10 3 5 20 20	TYP           40           40           5           20           20           45           45           45           60           60           5           20           20	MAX 60 10 40 25 70 70 70 70 200 150 50 50	UNITS ns ns ns ns ns ns ns ns ns ns ns
PARAMETER Driver Input to Output Driver Output Skew to Output Driver Rise or Fall Time Driver Enable to Output High Driver Enable to Output Low Driver Disable Time from Low Driver Disable Time from High Receiver Input to Output [ tpLH - tpHL ] Differential Receiver Skew Receiver Enable to Output Low Receiver Enable to Output High Receiver Disable Time from Low	SYMBOL       tPLH       tPHL       tSKEW       tR, tF       tZH       tZL       tLZ       tPLH, tPHL       tSKD       tZL       tZL       tSKD       tZL       tZL	$\label{eq:constraint} \hline \textbf{COND} \\ \hline Figures 10 and 12, R_{DIF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline Figures 10 and 12, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 11 and 13, C_{L} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline C_{L1} = C_{L2} = 100 \text{pF} \\ \hline Figures 10 and 14, R_{DIFF} \\ \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline \hline \hline \hline \hline Figures 9 and 15, C_{RL} \\ \hline $	ITIONS $FF = 54\Omega$ , $= 54\Omega$ , $CL1 = Cl$ X481E, MAX485E           X490EC/E, MA $= 100pF$ , S2 cl $= 100pF$ , S1 cl $= 15pF$ , S1 clo $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA $= 15pF$ , S2 clo           X481E, MAX485E           X490EC/E, MA           FF = 54Ω, $= 15pF$ , S1 clo $= 15pF$ , S1 clo $= 15pF$ , S2 clo $= 15pF$ , S1 clo	,MAX1487E X491EC/E losed losed sed sed x491EC/E X491EC/E sed sed sed sed	10 10 3 5 20	TYP           40           40           5           20           20           45           45           45           60           5           20           20           20           20           20           20           20           20           20           20           20           20           20	MAX 60 10 25 70 70 70 70 200 150 50 50 50 50	UNITS ns ns ns ns ns ns ns ns ns ns

MAX481E/MAX483E/MAX485E/MAX487E-MAX491E/MAX1487E



3

## SWITCHING CHARACTERISTICS—MAX481E/MAX485E, MAX490E/MAX491E, MAX1487E (continued)

 $(V_{CC} = 5V \pm 5\%, T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Enable from Shutdown to Output High (MAX481E)	tzh(shdn)	Figures 11 and 13, C <sub>L</sub> = 100pF, S2 closed		45	100	ns
Driver Enable from Shutdown to Output Low (MAX481E)	tzl(shdn)	Figures 11 and 13, C <sub>L</sub> = 100pF, S1 closed		45	100	ns
Receiver Enable from Shutdown to Output High (MAX481E)	tzh(shdn)	Figures 9 and 15, $C_L = 15pF$ , S2 closed, A - B = 2V		225	1000	ns
Receiver Enable from Shutdown to Output Low (MAX481E)	tzl(shdn)	Figures 9 and 15, $C_L$ = 15pF, S1 closed, B - A = 2V		225	1000	ns

#### SWITCHING CHARACTERISTICS—MAX483E, MAX487E/MAX488E/MAX489E

(V<sub>CC</sub> = 5V  $\pm$ 5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Input to Output	<b>t</b> PLH	Figures 10 and 12, $R_{DIFF} = 54\Omega$ ,	250	800	2000	nc
Driver input to Output	<b>t</b> PHL	$C_{L1} = C_{L2} = 100 \text{pF}$	250	800	2000	ns
Driver Output Skew to Output	tskew	Figures 10 and 12, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100 pF$		20	800	ns
Driver Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	Figures 10 and 12, R <sub>DIFF</sub> = 54 $\Omega$ , C <sub>L1</sub> = C <sub>L2</sub> = 100pF	250		2000	ns
Driver Enable to Output High	tzн	Figures 11 and 13, CL = 100pF, S2 closed	250		2000	ns
Driver Enable to Output Low	t <sub>ZL</sub>	Figures 11 and 13, C <sub>L</sub> = 100pF, S1 closed	250		2000	ns
Driver Disable Time from Low	tLZ	Figures 11 and 13, CL = 15pF, S1 closed	300		3000	ns
Driver Disable Time from High	tHZ	Figures 11 and 13, CL = 15pF, S2 closed	300		3000	ns
	<b>t</b> PLH	Figures 10 and 14, $R_{DIFF} = 54\Omega$ ,	250		2000	
Receiver Input to Output	<b>t</b> PHL	$C_{L1} = C_{L2} = 100 \text{pF}$	250		2000	ns
l t <sub>PLH</sub> - t <sub>PHL</sub> l Differential Receiver Skew	tskd	Figures 10 and 14, R <sub>DIFF</sub> = $54\Omega$ , C <sub>L1</sub> = C <sub>L2</sub> = 100pF		100		ns
Receiver Enable to Output Low	tzL	Figures 9 and 15, C <sub>RL</sub> = 15pF, S1 closed		25	50	ns
Receiver Enable to Output High	tzн	Figures 9 and 15, C <sub>RL</sub> = 15pF, S2 closed		25	50	ns
Receiver Disable Time from Low	tLZ	Figures 9 and 15, C <sub>RL</sub> = 15pF, S1 closed		25	50	ns
Receiver Disable Time from High	t <sub>HZ</sub>	Figures 9 and 15, C <sub>RL</sub> = 15pF, S2 closed		25	50	ns
Maximum Data Rate	fmax	tPLH, tPHL < 50% of data period	250			kbps
Time to Shutdown	<b>t</b> SHDN	MAX483E/MAX487E (Note 5)	50	200	600	ns
Driver Enable from Shutdown to Output High	tzh(shdn)	MAX483E/MAX487E, Figures 11 and 13, $C_L = 100pF$ , S2 closed			2000	ns
Driver Enable from Shutdown to Output Low	tzl(shdn)	MAX483E/MAX487E, Figures 11 and 13, $C_L = 100pF$ , S1 closed			2000	ns
Receiver Enable from Shutdown to Output High	tzh(shdn)	MAX483E/MAX487E, Figures 9 and 15, C <sub>L</sub> = 15pF, S2 closed			2500	ns
Receiver Enable from Shutdown to Output Low	tzl(shdn)	MAX483E/MAX487E, Figures 9 and 15, C <sub>L</sub> = 15pF, S1 closed			2500	ns

M/IXI/M

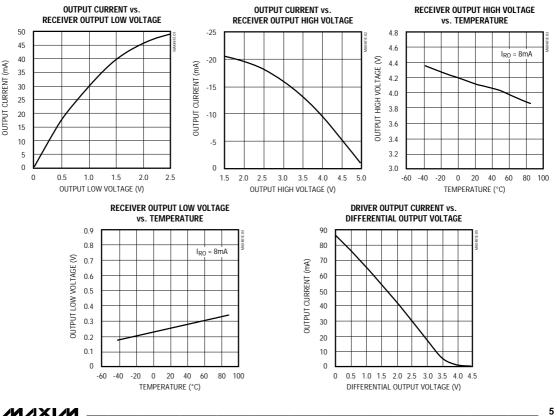
#### NOTES FOR ELECTRICAL/SWITCHING CHARACTERISTICS

- Note 1: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
- Note 2: All typical specifications are given for  $V_{CC} = 5V$  and  $T_A = +25^{\circ}C$ .
- Note 3: Supply current specification is valid for loaded transmitters when DE = 0V.
- Note 4: Applies to peak current. See Typical Operating Characteristics.

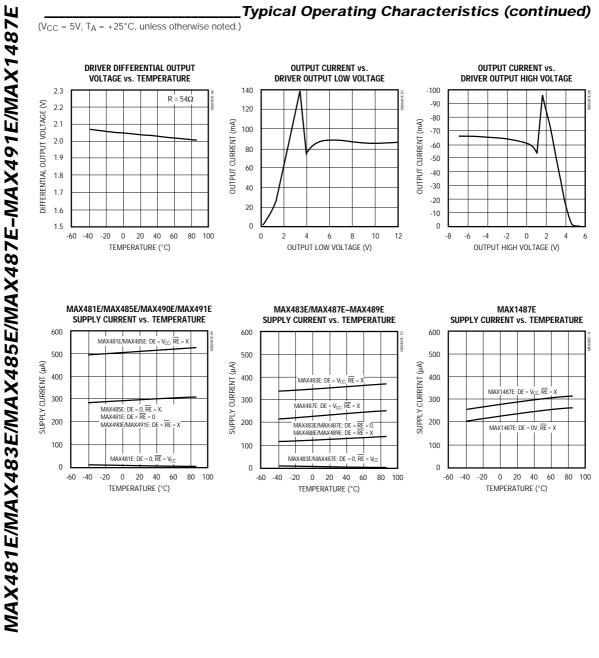
( $V_{CC} = 5V$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

Note 5: The MAX481E/MAX483E/MAX487E are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 50ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 600ns, the parts are guaranteed to have entered shutdown. See Low-Power Shutdown Mode section.

#### Typical Operating Characteristics



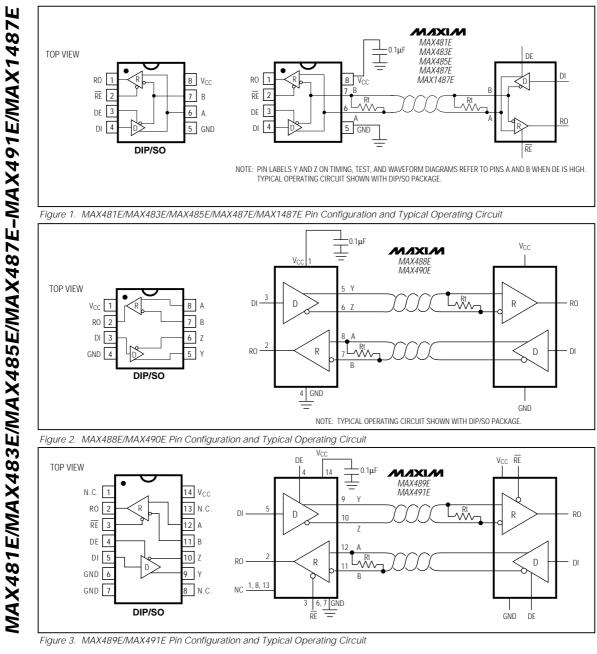
MAX481E/MAX483E/MAX485E/MAX487E-MAX491E/MAX1487E



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#### \_Pin Description

	PIN			
MAX481E/MAX483E MAX485E/MAX487E MAX1487E	MAX488E MAX490E	MAX489E MAX491E	NAME	FUNCTION
1	2	2	RO	Receiver Output: If A > B by 200mV, RO will be high; If A < B by 200mV, RO will be low.
2		3	RE	Receiver Output Enable. RO is enabled when $\overline{\text{RE}}$ is low; RO is high impedance when $\overline{\text{RE}}$ is high.
3	_	4	DE	Driver Output Enable. The driver outputs, Y and Z, are enabled by bringing DE high. They are high imped- ance when DE is low. If the driver outputs are enabled, the parts function as line drivers. While they are high impedance, they function as line receivers if RE is low.
4	3	5	DI	Driver Input. A low on DI forces output Y low and out- put Z high. Similarly, a high on DI forces output Y high and output Z low.
5	4	6, 7	GND	Ground
_	5	9	Y	Noninverting Driver Output
—	6	10	Z	Inverting Driver Output
6		_	A	Noninverting Receiver Input and Noninverting Driver Output
_	8	12	А	Noninverting Receiver Input
7	_	_	В	Inverting Receiver Input and Inverting Driver Output
—	7	11	В	Inverting Receiver Input
8	1	14	Vcc	Positive Supply: $4.75V \le V_{CC} \le 5.25V$
_	_	1, 8, 13	N.C.	No Connect—not internally connected



8

## ±15kV ESD-Protected, Slew-Rate-Limited, Low-Power, RS-485/RS-422 Transceivers

Function Tables (MAX481E/MAX483E/MAX485E/MAX487E/MAX1487E)

#### Table 1. Transmitting

	INPUTS			PUTS
RE	DE	DI	z	Y
Х	1	1	0	1
Х	1	0	1	0
0	0	Х	High-Z	High-Z
1	0	Х	High-Z*	High-Z*

X = Don't care

High-Z = High impedance \* Shutdown mode for MAX481E/MAX483E/MAX487E

#### \_Applications Information

The MAX481E/MAX483E/MAX485E/MAX487E–MAX491E and MAX1487E are low-power transceivers for RS-485 and RS-422 communications. These "E" versions of the MAX481, MAX483, MAX485, MAX487–MAX491, and MAX1487 provide extra protection against ESD. The rugged MAX481E, MAX483E, MAX485E, MAX497E– MAX491E, and MAX1487E are intended for harsh environments where high-speed communication is important. These devices eliminate the need for transient suppressor diodes and the associated high capacitance loading. The standard (non-"E") MAX481, MAX483, MAX485, MAX487–MAX491, and MAX1487 are recommended for applications where cost is critical.

The MAX481E, MAX485E, MAX490E, MAX491E, and MAX1487E can transmit and receive at data rates up to 2.5Mbps, while the MAX483E, MAX487E, MAX488E, and MAX489E are specified for data rates up to 250kbps. The MAX488E–MAX491E are full-duplex transceivers, while the MAX481E, MAX483E, MAX487E, and MAX1487E are half-duplex. In addition, driverenable (DE) and receiver-enable (RE) pins are included on the MAX481E, MAX483E, MAX487E, M

#### ±15kV ESD Protection

As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs have extra protection against static electricity. Maxim's engi-



#### Table 2. Receiving

	OUTPUT		
RE	DE	A-B	RO
0	0	≥ +0.2V	1
0	0	≤ -0.2V	0
0	0	Inputs open	1
1	0	Х	High-Z*

X = Don't care

High-Z = High impedance \* Shutdown mode for MAX481E/MAX483E/MAX487E

neers developed state-of-the-art structures to protect these pins against ESD of ±15kV without damage. The ESD structures withstand high ESD in all states: normal operation, shutdown, and powered down. After an ESD event, Maxim's MAX481E, MAX483E, MAX485E, MAX487E–MAX491E, and MAX1487E keep working without latchup.

ESD protection can be tested in various ways; the transmitter outputs and receiver inputs of this product family are characterized for protection to  $\pm 15$ kV using the Human Body Model.

Other ESD test methodologies include IEC10004-2 contact discharge and IEC1000-4-2 air-gap discharge (formerly IEC801-2).

#### ESD Test Conditions

ESD performance depends on a variety of conditions. Contact Maxim for a reliability report that documents test set-up, test methodology, and test results.

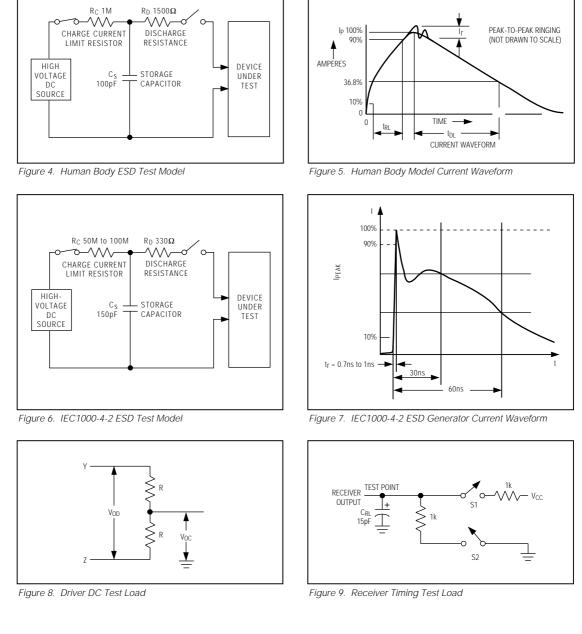
#### Human Body Model

Figure 4 shows the Human Body Model, and Figure 5 shows the current waveform it generates when discharged into a low impedance. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the test device through a  $1.5k\Omega$  resistor.

#### IEC1000-4-2

The IEC1000-4-2 standard covers ESD testing and performance of finished equipment; it does not specifically refer to integrated circuits (Figure 6).





**W** \X **W** 

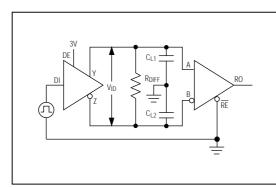


Figure 10. Driver/Receiver Timing Test Circuit

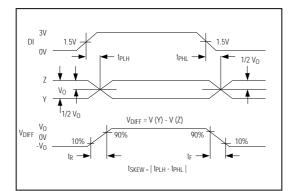


Figure 12. Driver Propagation Delays

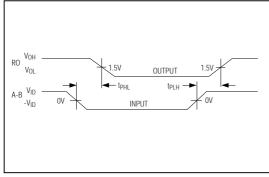
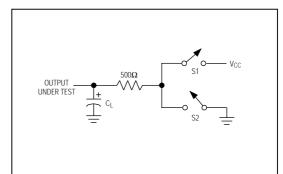


Figure 14. Receiver Propagation Delays





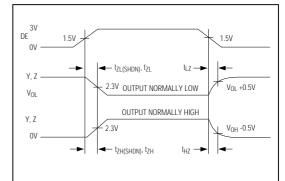


Figure 13. Driver Enable and Disable Times (except MAX488E and MAX490E)

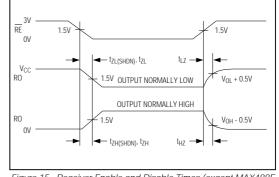


Figure 15. Receiver Enable and Disable Times (except MAX488E and MAX490E)

MAX481E/MAX483E/MAX485E/MAX487E-MAX491E/MAX1487E

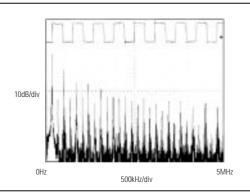


Figure 16. Driver Output Waveform and FFT Plot of MAX485E/MAX490E/MAX491E/MAX1487E Transmitting a 150kHz Signal

The major difference between tests done using the Human Body Model and IEC1000-4-2 is higher peak current in IEC1000-4-2, because series resistance is lower in the IEC1000-4-2 model. Hence, the ESD withstand voltage measured to IEC1000-4-2 is generally lower than that measured using the Human Body Model. Figure 7 shows the current waveform for the 8kV IEC1000-4-2 ESD contact-discharge test.

The air-gap test involves approaching the device with a charged probe. The contact-discharge method connects the probe to the device before the probe is energized.

#### Machine Model

The Machine Model for ESD tests all pins using a 200pF storage capacitor and zero discharge resistance. Its objective is to emulate the stress caused by contact that occurs with handling and assembly during manufacturing. Of course, all pins require this protection during manufacturing—not just inputs and outputs. Therefore, after PC board assembly, the Machine Model is less relevant to I/O ports.

#### MAX487E/MAX1487E: 128 Transceivers on the Bus

The 48k $\Omega$ , 1/4-unit-load receiver input impedance of the MAX487E and MAX1487E allows up to 128 transceivers on a bus, compared to the 1-unit load (12k $\Omega$  input impedance) of standard RS-485 drivers (32 transceivers maximum). Any combination of MAX487E/MAX1487E and other RS-485 transceivers with a total of 32 unit loads or less can be put on the bus. The MAX481E, MAX483E, MAX485E, and MAX488E–MAX491E have standard 12k $\Omega$  receiver input impedance.

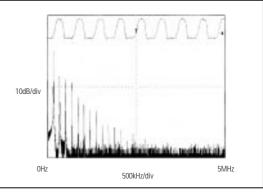


Figure 17. Driver Output Waveform and FFT Plot of MAX483E/MAX487E–MAX489E Transmitting a 150kHz Signal

#### MAX483E/MAX487E/MAX488E/MAX489E: Reduced EMI and Reflections

The MAX483E and MAX487E–MAX489E are slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Figure 16 shows the driver output waveform and its Fourier analysis of a 150kHz signal transmitted by a MAX481E, MAX485E, MAX490E, MAX491E, or MAX1487E. Highfrequency harmonics with large amplitudes are evident. Figure 17 shows the same information displayed for a MAX483E, MAX487E, MAX488E, or MAX489E transmitting under the same conditions. Figure 17's high-frequency harmonics have much lower amplitudes, and the potential for EMI is significantly reduced.

#### Low-Power Shutdown Mode (MAX481E/MAX483E/MAX487E)

A low-power shutdown mode is initiated by bringing both RE high and DE low. The devices will not shut down unless both the driver and receiver are disabled. In shutdown, the devices typically draw only  $0.5\mu$ A of supply current.

 $\overline{\text{RE}}$  and DE may be driven simultaneously; the parts are guaranteed not to enter shutdown if  $\overline{\text{RE}}$  is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts are guaranteed to enter shutdown.

For the MAX481E, MAX483E, and MAX487E, the t<sub>ZH</sub> and t<sub>ZL</sub> enable times assume the part was not in the low-power shutdown state (the MAX485E, MAX488E–MAX491E, and MAX1487E can not be shut down). The t<sub>ZH</sub>(SHDN) and t<sub>ZL</sub>(SHDN) enable times assume the parts were shut down (see *Electrical Characteristics*).

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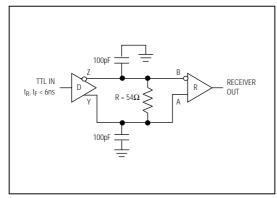


Figure 18. Receiver Propagation Delay Test Circuit

It takes the drivers and receivers longer to become enabled from the low-power shutdown state (tzH(SHDN), tzL(SHDN)) than from the operating mode (tzH, tzL). (The parts are in operating mode if the RE, DE inputs equal a logical 0,1 or 1,1 or 0, 0.)

#### **Driver Output Protection**

Excessive output current and power dissipation caused by faults or by bus contention are prevented by two mechanisms. A foldback current limit on the output stage provides immediate protection against short circuits over the whole common-mode voltage range (see Typical Operating Characteristics). In addition, a thermal shutdown circuit forces the driver outputs into a high-impedance state if the die temperature rises excessively

#### **Propagation Delay**

Many digital encoding schemes depend on the difference between the driver and receiver propagation delay times. Typical propagation delays are shown in Figures 19-22 using Figure 18's test circuit.

The difference in receiver delay times, tPLH - tPHL, is typically under 13ns for the MAX481E, MAX485E, MAX490E, MAX491E, and MAX1487E, and is typically less than 100ns for the MAX483E and MAX487E-MAX489F

The driver skew times are typically 5ns (10ns max) for the MAX481E, MAX485E, MAX490E, MAX491E, and MAX1487E, and are typically 100ns (800ns max) for the MAX483E and MAX487E-MAX489E.

**Typical Applications** The MAX481E, MAX483E, MAX485E, MAX487E-MAX491E, and MAX1487E transceivers are designed for bidirectional data communications on multipoint bus transmission lines. Figures 25 and 26 show typical network application circuits. These parts can also be used as line repeaters, with cable lengths longer than 4000 feet.

To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible. The slew-rate-limited MAX483E and MAX487E-MAX489E are more tolerant of imperfect termination. Bypass the Vcc pin with 0.1µF.

#### **Isolated RS-485**

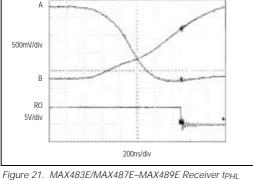
For isolated RS-485 applications, see the MAX253 and MAX1480 data sheets.

#### Line Length vs. Data Rate

The RS-485/RS-422 standard covers line lengths up to 4000 feet. Figures 23 and 24 show the system differential voltage for the parts driving 4000 feet of 26AWG twisted-pair wire at 110kHz into  $100\Omega$  loads.

M/IXI/N

## ±15kV ESD-Protected, Slew-Rate-Limited, Low-Power, RS-485/RS-422 Transceivers А 500mV/div В RO 5V/div 25ns/div Figure 19. MAX481E/MAX485E/MAX490E/MAX1487E Receiver **t**PHL



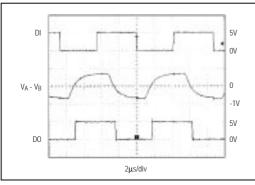


Figure 23. MAX481E/MAX485E/MAX490E/MAX491E/ MAX1487E System Differential Voltage at 110kHz Driving 4000ft of Cable

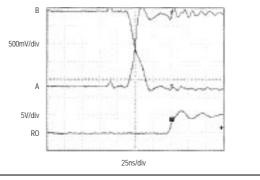


Figure 20. MAX481E/MAX485E/MAX490E/MAX491E/ MAX1487E Receiver tPLH

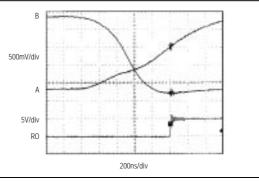


Figure 22. MAX483E/MAX487E–MAX489E Receiver tpLH

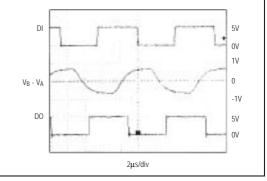


Figure 24. MAX483E/MAX1487E–MAX489E System Differential Voltage at 110kHz Driving 4000ft of Cable

M/IXI/M

MAX481E/MAX483E/MAX485E/MAX487E-MAX491E/MAX1487E

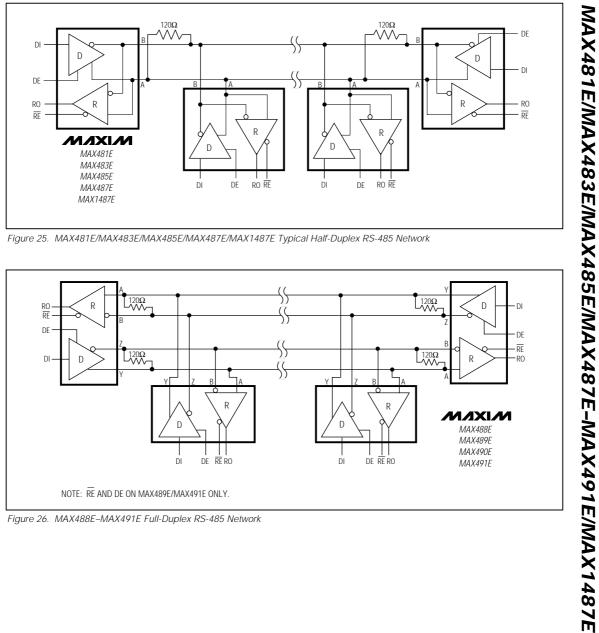


Figure 25. MAX481E/MAX483E/MAX485E/MAX487E/MAX1487E Typical Half-Duplex RS-485 Network

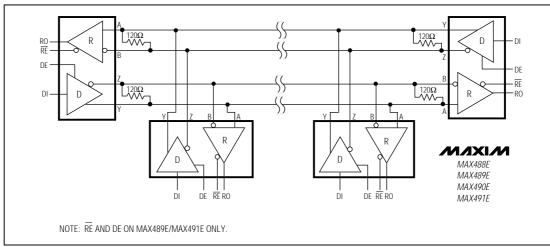


Figure 26. MAX488E–MAX491E Full-Duplex RS-485 Network

PART	TEMP. RANGE	PIN-PACKAGE
MAX483ECPA	0°C to +70°C	8 Plastic DIP
MAX483ECSA	0°C to +70°C	8 SO
MAX483EEPA	-40°C to +85°C	8 Plastic DIP
MAX483EESA	-40°C to +85°C	8 SO
MAX485ECPA	0°C to +70°C	8 Plastic DIP
MAX485ECSA	0°C to +70°C	8 SO
MAX485EEPA	-40°C to +85°C	8 Plastic DIP
MAX485EESA	-40°C to +85°C	8 SO
MAX487ECPA	0°C to +70°C	8 Plastic DIP
MAX487ECSA	0°C to +70°C	8 SO
MAX487EEPA	-40°C to +85°C	8 Plastic DIP
MAX487EESA	-40°C to +85°C	8 SO
MAX488ECPA	0°C to +70°C	8 Plastic DIP
MAX488ECSA	0°C to +70°C	8 SO
MAX488EEPA	-40°C to +85°C	8 Plastic DIP
MAX488EESA	-40°C to +85°C	8 SO

#### Ordering Information (continued)

PART	TEMP. RANGE	PIN-PACKAGE
MAX489ECPD	0°C to +70°C	14 Plastic DIP
MAX489ECSD	0°C to +70°C	14 SO
MAX489EEPD	-40°C to +85°C	14 Plastic DIP
MAX489EESD	-40°C to +85°C	14 SO
MAX490ECPA	0°C to +70°C	8 Plastic DIP
MAX490ECSA	0°C to +70°C	8 SO
MAX490EEPA	-40°C to +85°C	8 Plastic DIP
MAX490EESA	-40°C to +85°C	8 SO
MAX491ECPD	0°C to +70°C	14 Plastic DIP
MAX491ECSD	0°C to +70°C	14 SO
MAX491EEPD	-40°C to +85°C	14 Plastic DIP
MAX491EESD	-40°C to +85°C	14 SO
MAX1487ECPA	0°C to +70°C	8 Plastic DIP
MAX1487ECSA	0°C to +70°C	8 SO
MAX1487EEPA	-40°C to +85°C	8 Plastic DIP
MAX1487EESA	-40°C to +85°C	8 SO

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#### Chip Information

TRANSISTOR COUNT: 295

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